

**EUROCONTROL STANDARD DOCUMENT**

**FOR**

**SURVEILLANCE DATA EXCHANGE**

**Part 2b**

**Transmission of Monoradar Service Messages**

**SUR.ET1.ST05.2000-STD-02b-01**

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# DOCUMENT IDENTIFICATION SHEET

## DOCUMENT DESCRIPTION

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### Abstract

This document describes the application of ASTERIX to the transmission of monoradar service messages.

### Keywords

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The following table identifies all management authorities who have successively approved the present issue of this document.

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**DOCUMENT CHANGE RECORD**

The following table records the complete history of the successive editions of the present document.

<b>EDITION</b>	<b>DATE</b>	<b>REASON FOR CHANGE</b>	<b>SECTIONS PAGES AFFECTED</b>
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Proposed Ed 1.26	November 2000	<ul style="list-style-type: none"> <li>• Sector Crossing Messages made optional.</li> <li>• Items 050 and 060 made optional.</li> </ul>	4.3 See respective Data Items

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## **1. INTRODUCTION**

### **1.1 Scope**

**1.1.1** This document describes the message structure for the transmission of monoradar service messages, from a radar station (conventional Secondary Surveillance Radar (SSR), monopulse, Mode S, conventional primary radar or primary radar using Moving Target Detection (MTD) processing), to one or more Surveillance Data Processing (SDP) Systems.

**1.1.2** Monoradar service messages are data out of Data Category 034.

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## **2. REFERENCES**

### **2.1 General**

The following Documents and Standards contain provisions which, through references in this text, constitute provisions of this Eurocontrol Standard Document.

At the time of publication of this Eurocontrol Standard Document, the editions indicated for the referenced documents and standards were valid.

Any revision of the referenced ICAO Documents shall be immediately taken into account to revise this Eurocontrol Standard Document.

Revisions of the other referenced documents shall not form part of the provisions of this Eurocontrol Standard Document until they are formally reviewed and incorporated into this Eurocontrol Standard Document.

In the case of a conflict between the requirements of this Eurocontrol Standard Document and the contents of the other referenced documents, this Eurocontrol Standard Document shall take precedence.

### **2.2 Reference Documents**

1. Eurocontrol Standard 000-1-92. Directives for the Uniform Drafting and Presentation of Eurocontrol Standard Documents. 1992.
2. Eurocontrol Standard SUR.ET1.ST05.2000-STD-01-01. All Purpose Structured Eurocontrol Surveillance Information Exchange - ASTERIX. Edition 1.26, Proposed, November 2000
3. Eurocontrol Standard SUR.ET1.1000-STD-01-01. Radar Surveillance in En-Route Airspace and Major Terminal Areas.

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### 3. DEFINITIONS, ACRONYMS AND ABBREVIATIONS

#### 3.1 Definitions

For the purposes of this Eurocontrol Document, the following definitions shall apply:

- 3.1.1 Catalogue of Data Items:** List of all the possible Data Items of each Data Category describing the Data Items by their reference, structure, size and units (where applicable).
- 3.1.2 Data Block:** Unit of information seen by the application as a discrete entity by its contents. A Data Block contains one or more Record(s) containing data of the same Category.
- 3.1.3 Data Category:** Classification of the data in order to permit inter alia an easy identification.
- 3.1.4 Data Field:** Physical implementation for the purpose of communication of a Data Item, it is associated with a unique Field Reference Number and is the smallest unit of transmitted information.
- 3.1.5 Data Item:** The smallest unit of information in each Data Category.
- 3.1.6 Record:** A collection of transmitted Data Fields of the same Category preceded by a Field Specification field, signalling the presence/absence of the various Data Fields
- 3.1.7 User Application Profile:** The mechanism for assigning Data Items to Data Fields, and containing all necessary information which needs to be standardised for the successful encoding and decoding of the messages.

**3.2 Acronyms and Abbreviations**

For the purposes of this Eurocontrol Document the following shall apply:

<b>ASTERIX</b>	All Purpose STructured Eurocontrol suRveillance Information EXchange
<b>CAT</b>	Data Category
<b>COMT</b>	Communications Team (EATMP)
<b>EATMP</b>	European Air Traffic Control Management Programme
<b>FRN</b>	Field Reference Number
<b>FSPEC</b>	Field Specification
<b>FX</b>	Field Extension Indicator
<b>ICAO</b>	International Civil Aviation Organization
<b>LEN</b>	Length Indicator
<b>LSB</b>	Least Significant Bit
<b>MSSR</b>	Monopulse Secondary Surveillance Radar
<b>MTD</b>	Moving Target Detection
<b>NM</b>	Nautical Mile, unit of distance (1852 metres)
<b>PSR</b>	Primary Surveillance Radar
<b>RDP</b>	Radar Data Processing (System)
<b>RDPC</b>	Radar Data Processing Chain
<b>REP</b>	Field Repetition Indicator
<b>s</b>	second, unit of time
<b>SAC</b>	System Area Code
<b>SDP</b>	Surveillance Data Processing (system)
<b>SIC</b>	System Identification Code
<b>SP</b>	Special Purpose Indicator
<b>SSR</b>	Secondary Surveillance Radar
<b>STFRDE</b>	Surveillance Task Force on Radar Data Exchange
<b>SURT</b>	Surveillance Team (EATMP)
<b>UAP</b>	User Application Profile (see Definitions)
<b>UTC</b>	Co-ordinated Universal Time

## 4. GENERAL PRINCIPLES

### 4.1 General

The transmission of monoradar information shall require the transmission of two types of messages:

- data messages or radar target reports containing plot or track information (not covered by this document);
- radar service messages used to signal status information of the radar station to the user systems.

### 4.2 Time Management

Time Management principles apply only to conventional rotating antennas.

#### 4.2.1 Definition

The sector time stamp shall be consistent with the reported sector azimuth.

#### 4.2.2 Requirements for Time Stamping

The timestamping shall comply with the Coordinated Universal Time (UTC) as specified in ICAO Annex 5. It shall be used to time stamp radar data.

### 4.3 North Marker and Sector Crossing Messages

This paragraph only applies to conventional rotating antennas.

At every north crossing one and only one North Marker Message shall be transmitted. The highest priority shall be given to the transmission of the North Marker Message; this shall not be delayed by the plot processing activities.

Sector Crossing Messages are optional messages. When used, they shall always be thirty-two per revolution.

### 4.4 Unused Bits in Data Items.

Decoders of ASTERIX data **shall never assume and rely on** specific settings of spare or unused bits. However in order to improve the readability of binary dumps of ASTERIX records, it is recommended to set all spare bits to zero.

## 4.5 Definitions and Addressing Concepts

In order to address radar sources in an unambiguous way, a simple abstract model for concepts like sensors or radar systems has been designed.

### 4.5.1 Radar Sensor

In the framework of Category 034 a Radar Sensor is a detection/measurement device, either of the Primary (PSR) or Secondary Surveillance Radar (SSR, MSSR) type, which uses a single rotating antenna assembly.

### 4.5.2 Radar System

In the framework of Category 034 a Radar System is a construction, consisting of either **one single** sensor or a **combination of two** sensors of different types. In the case of combined sensors it is assumed that the respective antenna subsystems are configured, such that:

- a coincidence in target detection is guaranteed;
- a single co-ordinate reference point is used.

### 4.5.3 Combination of Target Reports

The Radar Data Combiner is a function which combines (merges) the digitized target reports (plots) from two sensors constituting one Radar System.

#### 4.5.4 Addressing Concepts: Assigning SAC/SIC Codes

By convention a dedicated and unambiguous SAC/SIC code shall be assigned to every Radar System.

##### EXAMPLES

1. A back-to-back configuration of two PSRs with an on-mounted SSR antenna each, is considered as two Radar Systems, being addressed via two SAC/SIC codes.
2. A main tower carrying a combined PSR/SSR radar station, supplemented with a standby tower at several hundreds of meters from the main tower and supporting a single back-up SSR station, shall be considered as two independent Radar Systems. It is irrelevant whether both radar systems are synchronized or not, and in addition whether only one Radar System at a time transmits its data or both Radar Systems simultaneously.
3. Two distinct radar heads, located at close distance, whose data is processed in a time-exclusive way by the same plot processor equipment may be considered as a single Radar System, using a single SAC/SIC address, provided that:
  - the same geographical reference point is used, irrespective of whether the data of head#1 or head#2 is selected;
  - the access lines to the site carry only the data of one head at a time.

Where the above conditions are not simultaneously met, it is imperative to assign two SAC/SIC codes.

#### 4.6 Radar Service Messages

##### 4.6.1 Types of Radar Service Messages

Four types of radar service messages have been identified:

- Sector Crossing Messages;
- North Marker Messages;
- Geographical Filtering Messages;
- Jamming Strobe Messages.

##### 4.6.1.1 Sector Crossing Messages

4.6.1.1.1 When Sector Crossing messages are used, the transmission of 32 messages shall be synchronised (possibly with some delay) with the antenna rotation.

4.6.1.1.2 Sector crossing messages shall be time-stamped. The time information should be the time at which the antenna has crossed the azimuth defining the beginning of the sector, and not the time of transmission of the message.

4.6.1.1.3 By convention, the sector 0 crossing message shall signal the crossing of the North azimuth. It may contain more information than other sector crossing messages.

**4.6.1.2 North Marker Messages**

**4.6.1.2.1** These messages shall signal, independently of the sector crossing messages and as quickly as possible, the crossing of the local geographical North azimuth by the antenna.

**4.6.1.2.2** The North marker message shall not replace the sector 0 crossing message. The transmission of the sector 0 crossing messages can be delayed like other sector crossing messages.

**4.6.1.3 Geographical Filtering Messages**

These messages shall be sent to inform the user system(s) on the activation and the de-activation of geographical selective plots or tracks filtering processes.

**4.6.1.4 Jamming Strobe Messages**

These messages shall be sent to indicate an area where jamming strobe has been detected.

**4.6.2 User Application Profile and Data Block**

**4.6.2.1** A single UAP has been standardised and shall be used to transmit service messages from a radar station to user RDP systems.

**4.6.2.2** Data Blocks containing radar service messages shall have the following layout:

<b>CAT = 034</b>	<b>LEN</b>	<b>FSPEC</b>	Items of the first record	<b>FSPEC</b>	Items of the last record
------------------	------------	--------------	---------------------------	--------------	--------------------------

Where:

- CAT = 034 is a one-octet field indicating that the Data Block contains service messages;
- LEN is a two-octet field indicating the total length in octets of the Data Block, including the CAT and LEN fields;
- FSPEC is the Field Specification.

**4.7 Composition of Messages**

**4.7.1** Messages shall be composed of Data Items assembled in the order defined by the Field Reference Number (FRN) in the associated UAP.

**4.7.2** When sent, items shall always be transmitted in a Record with the corresponding FSPEC bits set to one.



## 5. LAYOUT OF RADAR SERVICE MESSAGES

### 5.1 Standard Data Items

The standardised Data Items which shall be used for the transmission of radar service messages are defined in Table 4 and described in the following pages.

**Table 4 - Standard Data Items of Category 034**

<b>Data Item Ref. No.</b>	<b>Description</b>	<b>System Units</b>
I034/000	Message Type	N.A.
I034/010	Data Source Identifier	N.A.
I034/020	Sector Number	$360^\circ/(2^8)$
I034/030	Time of Day	1/128 s
I034/041	Antenna Rotation Period	1/128 s
I034/050	System Configuration & Status	N.A.
I034/060	System Processing Mode	N.A.
I034/070	Message Count Values	N.A.
I034/090	Collimation Error	Range: 1/128 NM Azimuth: $360^\circ/(2^{14})$
I034/100	Generic Polar Window	RHO: 1/256 NM THETA: $360^\circ/(2^{16})$
I034/110	Data Filter	N.A.
I034/120	3D-position of source	Height : 1 m Latitude: $180^\circ/(2^{23})$ Longitude: $180^\circ/(2^{23})$

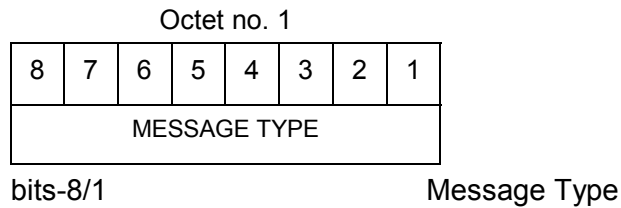
## 5.2 Description of Standard Data Items

### 5.2.1 Data Item I034/000, Message Type

**Definition :** This Data Item allows for a more convenient handling of the messages at the receiver side by further defining the type of transaction.

**Format :** One-octet fixed length Data Item.

**Structure:**



**Encoding Rule:**

This data item shall be present in every ASTERIX record.

#### NOTES

1. In applications where transactions of various types are exchanged, the Message Type Data Item facilitates the proper message handling at the receiver side.
2. All Message Type values are reserved for common standard use.
3. The following set of Message Types are standardised for Category 034 records:
  - 001 North Marker message
  - 002 Sector crossing message
  - 003 Geographical filtering message
  - 004 Jamming Strobe message
4. The list of items present for the four message types is defined in the following table.  
M stands for mandatory, O for optional, X for never present.

**Table 1 Message Types**

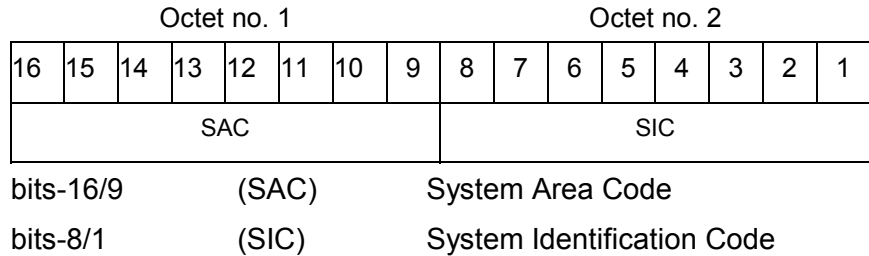
Type Item	001 North Marker	002 Sector Crossing	003 Geographical Filtering	004 Jamming Strobe
I034/000 Message Type	M	M	M	M
I034/010 Data Source Identifier	M	M	M	M
I034/020 Sector Number	X	M	X	X
I034/030 Time of Day	M	M	O	O
I034/041 Antenna Rotation Period	O	X	X	X
I034/050 System Configuration & Status	O	O	X	X
I034/060 System Processing Mode	O	O	X	X
I034/070 Message Count Values	O	O	X	X
I034/090 Collimation Error	O	O	X	X
I034/100 Generic Polar Window	X	X	O	M
I034/110 Data Filter	X	X	M	X
I034/120 3D-position of source	O	X	X	X

**5.2.2 Data Item I034/010, Data Source Identifier**

**Definition :** Identification of the radar station from which the data are received.

**Format :** Two-octet fixed length Data Item.

**Structure:**



**Encoding Rule:**

See table in I034/000.

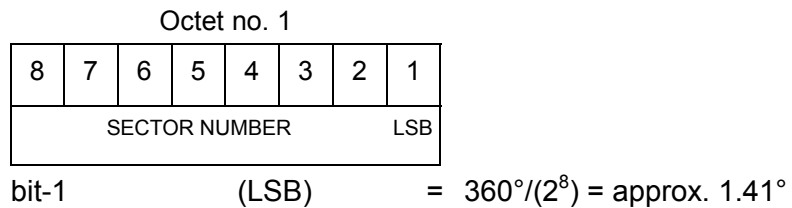
**NOTE** - The defined SACs are listed in Part 1, Table 2 [Ref. 2]

**5.2.3 Data Item I034/020, Sector Number**

**Definition :** Eight most significant bits of the antenna azimuth defining a particular azimuth sector.

**Format :** One-octet fixed length Data Item.

**Structure:**



**Encoding Rule:**

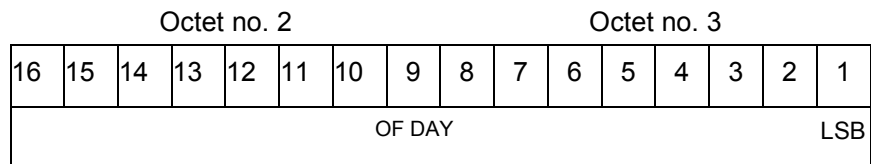
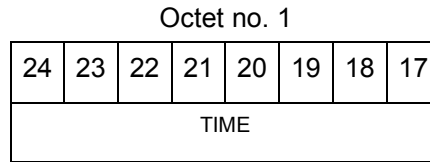
See Table in I034/000.

**5.2.4 Data Item I034/030, Time of Day**

**Definition :** Absolute time stamping expressed as UTC time.

**Format :** Three-octet fixed length Data Item.

**Structure:**



bit-1 (LSB) =  $(2^{-7})s = 1/128 s$

**Encoding Rule:**

See Table in I034/000.

For the message types where this data item is mandatory, it shall be sent, except in case of failure of all sources of time stamping. Every radar station using ASTERIX shall be equipped with at least one synchronised time source. The time information, coded in three octets, shall reflect the exact time of an event (crossing of the azimuth defining the beginning of a sector by the antenna), expressed as a number of 1/128 s elapsed since last midnight.

**NOTES**

1. The time of day value is reset to zero each day at midnight.

**5.2.5 Data Item I034/041, Antenna Rotation Speed**

**Definition :** Antenna rotation period as measured between two consecutive North crossings or as averaged during a period of time.

**Format :** Two-octet fixed length Data Item.

**Structure:**

Octet no. 1								Octet no. 2							
16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
ANTENNA ROTATION SPEED															LSB

$$\text{bit-1} \quad \quad \quad (\text{LSB}) \quad \quad \quad = (2^{-7}) \text{ s} = 1/128 \text{ s}$$

**Encoding Rule:**

See table in I034/000.

**NOTE -** This item represents the antenna rotation period as measured by the radar station between two consecutive North crossings, or a calculated antenna rotation speed as averaged during a period of time, or during a number of antenna rotation scans.

### 5.2.6 Data Item I034/050, System Configuration and Status

**Definition :** Information concerning the configuration and status of a System.

**Format :** Compound Data Item, comprising an extensible primary subfield (initially one octet; one octet extents), followed by a variable number of secondary subfields.

**Structure of  
Primary Subfield:**

Octet no. 1							
8	7	6	5	4	3	2	1
COM	0	0	PSR	SSR	MDS	0	FX

bit-8	(COM)	Subfield #1: Common Part = 0 Absence of Subfield #1 = 1 Presence of Subfield #1
bit-7	(Spare)	Subfield #2: Spare Subfield = 0 Absence of Subfield #2 = 1 Presence of Subfield #2
bit-6	(Spare)	Subfield #3: Spare Subfield = 0 Absence of Subfield #3 = 1 Presence of Subfield #3
bit-5	(PSR)	Subfield #4: Specific Status for PSR Sensor = 0 Absence of Subfield #4 = 1 Presence of Subfield #4
bit-4	(SSR)	Subfield #5: Specific Status for SSR Sensor = 0 Absence of Subfield #5 = 1 Presence of Subfield #5
bit-3	(MDS)	Subfield #6: Specific Status for Mode S Sensor = 0 Absence of Subfield #6 = 1 Presence of Subfield #6
bit-2	(Spare)	Subfield #7: Spare Subfield = 0 Absence of Subfield #7 = 1 Presence of Subfield #7
bit-1	(FX)	= 0 End of Primary Subfield = 1 Extension of Primary Subfield into next octet

**Structure of  
COM Subfield:**

The first Secondary Subfield (COM) contains the status of the common elements of a System.

Octet no. 1

8	7	6	5	4	3	2	1
NOGO	RDPC	RDPR	OVL RDP	OVL XMT	MSC	TSV	0

bit-8	(NOGO)	Operational Release Status of the System	= 0 System is released for operational use = 1 Operational use of System is inhibited, i.e. the data shall be discarded by an operational SDPS
bit-7	(RDPC)	Radar Data Processor Chain Selection Status	= 0 RDPC-1 selected = 1 RDPC-2 selected
bit-6	(RDPR)	Event to signal a reset/restart of the selected Radar Data Processor Chain, i.e. expect a new assignment of track numbers	= 0 Default situation = 1 Reset of RDPC
bit-5	(OVL RDP)	Radar Data Processor Overload Indicator	= 0 Default, no overload = 1 Overload in RDP
bit-4	(OVL XMT)	Transmission Subsystem Overload Status	= 0 Default, no overload = 1 Overload in transmission subsystem
bit-3	(MSC)	Monitoring System Connected Status	= 0 Monitoring system connected = 1 Monitoring system disconnected
bit-2	(TSV)	Time Source Validity	= 0 valid = 1 invalid
bit-1	(Spare)	Set to zero	

**NOTES**

1. A time source is considered as valid when either externally synchronised or running on a local oscillator within the required accuracy of UTC.
2. Bit-6 (RDPR) is sent only once after the event.



**Structure of PSR Subfield:  
Specific Status information for a PSR sensor**

Octet no. 1

8	7	6	5	4	3	2	1
ANT	CH-A/B		OVL	MSC	0	0	0

bit-8	(ANT)	Selected antenna = 0 antenna 1 = 1 antenna 2
bits-7/6	(CH-A/B)	Channel A/B selection status = 00 No channel selected = 01 Channel A only selected = 10 Channel B only selected = 11 Diversity mode ; Channel A and B selected
bit-5	(OVL)	Overload condition = 0 No overload = 1 Overload
bit-4	(MSC)	Monitoring System Connected Status: = 0 Monitoring system connected = 1 Monitoring system disconnected
bits-3/1	(Spare)	Spare bit set to 0

**Structure of SSR Subfield:  
Specific Status information for a SSR sensor**

Octet no. 1

8	7	6	5	4	3	2	1
ANT	CH-A/B		OVL	MSC	0	0	0

bit-8	(ANT)	Selected antenna = 0 antenna 1 = 1 antenna 2
bits-7/6	(CH-A/B)	Channel A/B selection status = 00 No channel selected = 01 Channel A only selected = 10 Channel B only selected = 11 Invalid combination
bit-5	(OVL)	Overload condition = 0 No overload = 1 Overload
bit-4	(MSC)	Monitoring System Connected Status: = 0 Monitoring system connected = 1 Monitoring system disconnected
bits-3/1	(Spare)	Spare bit set to 0

**Structure of MDS Subfield:  
Specific Status information for a Mode S sensor**

Octet no. 1							Octet no. 2								
16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
ANT	CH-A/B		OVL SUR	MSC	SCF	DLF	OVL SCF	OVL DLF	0	0	0	0	0	0	0

bit-16	(ANT )	Selected antenna = 0 antenna 1 = 1 antenna 2
bits-15/14	(CH-A/B)	Channel A/B selection status for surveillance = 00 No channel selected = 01 Channel A only selected = 10 Channel B only selected = 11 Illegal combination
bit-13	(OVL SUR)	Overload condition = 0 No overload = 1 Overload
bit-12	(MSC)	Monitoring System Connected Status: = 0 Monitoring system connected = 1 Monitoring system disconnected
bit-11	(SCF)	Channel A/B selection status for Surveillance Co-ordination Function = 0 Channel A in use = 1 Channel B in use
bit-10	(DLF)	Channel A/B selection status for Data Link Function = 0 Channel A in use = 1 Channel B in use
bit-9	(OVL SCF)	Overload in Surveillance Co-ordination Function = 0 No overload = 1 Overload
bit-8	(OVL DLF)	Overload in Data Link Function = 0 No overload = 1 Overload
bits 7/1	(Spare)	Spare bit set to 0

**Encoding Rule:**

See Table in I034/000.

**5.2.7 Data Item I034/060, System Processing Mode**

**Definition :** Status concerning the processing options, in use during the last antenna revolution, for the various Sensors, composing the System.

**Format :** Compound Data Item, comprising an extensible primary subfield (initially one octet; one octet extents), followed by a variable number of secondary subfields.

**Structure of  
Primary Subfield:**

Octet no. 1							
8	7	6	5	4	3	2	1
COM	0	0	PSR	SSR	MDS	0	FX

bit-8	(COM)	Subfield #1: Common Part = 0 Absence of Subfield #1 = 1 Presence of Subfield #1
bit-7	(Spare)	Subfield #2: Spare Subfield = 0 Absence of Subfield #2 = 1 Presence of Subfield #2
bit-6	(Spare)	Subfield #3: Spare Subfield = 0 Absence of Subfield #3 = 1 Presence of Subfield #3
bit-5	(PSR)	Subfield #4: Specific Processing Mode information for PSR Sensor = 0 Absence of Subfield #4 = 1 Presence of Subfield #4
bit-4	(SSR)	Subfield #5: Specific Processing Mode information for SSR Sensor = 0 Absence of Subfield #5 = 1 Presence of Subfield #5
bit-3	(MDS)	Subfield #6: Specific Processing Mode information for Mode S Sensor = 0 Absence of Subfield #6 = 1 Presence of Subfield #6
bit-2	(Spare)	Subfield #7: Spare Subfield = 0 Absence of Subfield #7 = 1 Presence of Subfield #7
bit-1	(FX)	= 0 End of Primary Subfield = 1 Extension of Primary Subfield into next octet

**Structure of  
COM Subfield:**

The first Secondary Subfield (COM) defines the processing modes of the common elements of a System.

Octet no. 1

8	7	6	5	4	3	2	1
0	RED-RDP			RED-XMT			0

bit-8	(Spare)	Fixed setting to zero
bits7/5	(RED-RDP)	Reduction Steps in use for an overload of the RDP = 000 No reduction active = 001 Reduction step 1 active = 010 Reduction step 2 active = 011 Reduction step 3 active = 100 Reduction step 4 active = 101 Reduction step 5 active = 110 Reduction step 6 active = 111 Reduction step 7 active
bits-4/2	(RED-XMT)	Reduction Steps in use for an overload of the Transmission subsystem = 000 No reduction active = 001 Reduction step 1 active = 010 Reduction step 2 active = 011 Reduction step 3 active = 100 Reduction step 4 active = 101 Reduction step 5 active = 110 Reduction step 6 active = 111 Reduction step 7 active
bit-1	(Spare)	= 0 Spare bit, fixed set to zero

**Structure of PSR Subfield:  
Specific Processing Mode information for a PSR sensor**

Octet no. 1

8	7	6	5	4	3	2	1
POL	RED-RAD			STC		0	0

bit-8	(POL)	Polarization in use by PSR = 0 Linear polarization = 1 Circular polarization
bits-7/5	(RED-RAD)	Reduction Steps in use as result of an overload within the PSR subsystem = 000 No reduction active = 001 Reduction step 1 active = 010 Reduction step 2 active = 011 Reduction step 3 active = 100 Reduction step 4 active = 101 Reduction step 5 active = 110 Reduction step 6 active = 111 Reduction step 7 active
bits-4/3	(STC)	Sensitivity Time Control Map in use = 00 STC Map-1 = 01 STC Map-2 = 10 STC Map-3 = 11 STC Map-4
bits-2/1	(Spare)	Spare bits; fixed set to zero

**Structure of SSR Subfield:  
 Specific Processing Mode information for a SSR sensor**

Octet no. 1

8	7	6	5	4	3	2	1
RED-RAD			0	0	0	0	0

bits-8/6 (RED-RAD) Reduction Steps in use as result of an overload within the SSR subsystem  
 = 000 No reduction active  
 = 001 Reduction step 1 active  
 = 010 Reduction step 2 active  
 = 011 Reduction step 3 active  
 = 100 Reduction step 4 active  
 = 101 Reduction step 5 active  
 = 110 Reduction step 6 active  
 = 111 Reduction step 7 active

bits-5/1 (Spare) Spare bits; fixed set to zero

**Structure of MDS Subfield:  
Specific Processing Mode information for a Mode S Sensor**

Octet no. 1

8	7	6	5	4	3	2	1
RED-RAD			CLU	0	0	0	0

bits-8/6	(RED-RAD)	Reduction Steps in use as result of an overload within the Mode S subsystem = 000 No reduction active = 001 Reduction step 1 active = 010 Reduction step 2 active = 011 Reduction step 3 active = 100 Reduction step 4 active = 101 Reduction step 5 active = 110 Reduction step 6 active = 111 Reduction step 7 active
bit-5	(CLU)	Cluster State = 0 Autonomous = 1 Not autonomous
bits-4/1	(Spare)	Spare bits; fixed set to zero

**Encoding Rule:**

See Table in I034/000.

**NOTE** - Applicable to all defined secondary subfields. The actual mapping between the up to seven data reduction steps and their associated data reduction measures is not subject to standardisation.



**5.2.8 Data Item I034/070, Message Count Values**

**Definition :** Message Count values, according the various types of messages, for the last completed antenna revolution, counted between two North crossings

**Format :** Repetitive Data Item, starting with a one-octet Field Repetition Indicator (REP) followed by at least one message counter of two-octet length.

**Structure:**

Octet no. 1

24	23	22	21	20	19	18	17
REP							

Octet no. 2							Octet no. 3								
16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
TYP						COUNTER									

- bits-24/17                      (REP)      Number of counters following
- bits16/12                      (TYP)      Type of message counter, encoded as follows
  - = 0 No detection (number of misses)
  - = 1 Single PSR target reports
  - = 2 Single SSR target reports (Non-Mode S)
  - = 3 SSR+PSR target reports (Non-Mode S)
  - = 4 Single All-Call target reports (Mode S)
  - = 5 Single Roll-Call target reports (Mode S)
  - = 6 All-Call + PSR (Mode S) target reports
  - = 7 Roll-Call + PSR (Mode S) target reports
  - = 8 Filter for Weather data
  - = 9 Filter for Jamming Strobe
  - = 10 Filter for PSR data
  - = 11 Filter for SSR/Mode S data
  - = 12 Filter for SSR/Mode S+PSR data
  - = 13 Filter for Enhanced Surveillance data
  - = 14 Filter for PSR+Enhanced Surveillance
  - = 15 Filter for PSR+Enhanced Surveillance + SSR/Mode S data not in Area of Prime Interest
  - = 16 Filter for PSR+Enhanced Surveillance + all SSR/Mode S data
- bits-11/1                      (COUNTER)      11-bit counter value

**Encoding Rule:**

See Table in I034/000.

**5.2.9 Data Item I034/090, Collimation Error**

**Definition :** Averaged difference in range and in azimuth for the primary target position with respect to the SSR target position as calculated by the radar station.

**Format :** Two-octet fixed length Data Item.

**Structure:**

Octet no. 1								Octet no. 2							
16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
RANGE ERROR								AZIMUTH ERROR							
								LSB							

bit-9 (LSB) = 1/128 NM

bit-1 (LSB) =  $360^\circ / (2^{14}) = \text{approx. } 0.022^\circ$

**Encoding Rule:**

See Table in I034/000.

**NOTE** - Negative values are coded in two's complement form.

**5.2.10 Data Item I034/100, Generic Polar Window**

**Definition :** Geographical window defined in polar co-ordinates.

**Format :** Eight-octet fixed length Data Item.

**Structure:**

Octet no. 1								Octet no. 2							
64	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49
RHO-START														LSB	

Octet no. 3								Octet no. 4							
48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33
RHO-END														LSB	

Octet no. 5								Octet no. 6							
32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17
THETA-START														LSB	

Octet no. 7								Octet no. 8							
16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
THETA-END														LSB	

bit-49 (LSB) = 1/256 NM.  
Max. Range = 256 NM

bit-33 (LSB) = 1/256 NM.  
Max. Range = 256 NM

bit-17 (LSB) =  $360^\circ / (2^{16}) = \text{approx. } 0.0055^\circ$

bit-1 (LSB) =  $360^\circ / (2^{16}) = \text{approx. } 0.0055^\circ$

Examples of Geographical windows:

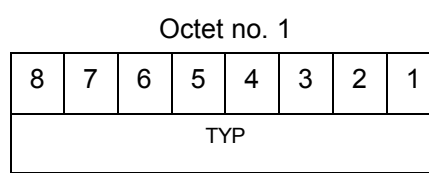
Polar Cell	Rho_start	Rho_end	Theta_start	Theta_end
Azimuth Sector	0	256 NM	Theta_start	Theta_end
Range Ring	Rho_start	Rho_end	0	360°
Total Coverage	0	256 NM	0	360°

**Encoding Rule:**

See Table in I034/000.

This data item shall be sent when:

- indicating a geographical filtering,
- indicating a jamming strobe area.

**5.2.11 I034/110 Data Filter****Definition :** Data Filter, which allows suppression of individual data types.**Format :** One octet fixed length Data Item.**Structure:** Structure:

- bits 8/1 (TYP) = 0 invalid value  
 = 1 Filter for Weather data  
 = 2 Filter for Jamming Strobe  
 = 3 Filter for PSR data  
 = 4 Filter for SSR/Mode S data  
 = 5 Filter for SSR/Mode S + PSR data  
 = 6 Enhanced Surveillance data  
 = 7 Filter for PSR+Enhanced Surveillance data  
 = 8 Filter for PSR+Enhanced Surveillance  
 + SSR/Mode S data not in Area of  
 Prime Interest  
 = 9 Filter for PSR+Enhanced Surveillance  
 + all SSR/Mode S data

**Encoding Rule:**

See Table in I034/000.

See also encoding rules for I034/100.

**NOTES**

1. This Data Item is often used in conjunction with I034/100 and represents a Data Filter for a specific geographical subarea. A Data Source may have zero, one or multiple data filters active at any time.
2. If I034/110 is not accompanied with I034/100, then the Data Filter is valid throughout the total area of coverage.

**5.2.12 I034/120 3D-Position Of Data Source.**

**Definition :** 3D-Position of Data Source in WGS 84 Co-ordinates.

**Format :** Eight-octet fixed length Data Item.

**Structure:**

Octet no. 1								Octet no. 2							
64	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49
Height in WGS 84															LSB

Octet no. 3								Octet no. 4							
48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33
Latitude in WGS 84															

Octet no. 5								Octet no.6								
32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	
								LSB								

Octet no.7								Octet no.8							
16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
Longitude in WGS 84															LSB

bits-64/49	(Height of Data Source)	Signed Height of the Data Source, expressed in meters above WGS 84 reference ellipsoid.
Bit-49	(LSB)	= 1 metre
Bits-48/25	(Latitude)	Latitude in WGS 84 expressed in two's complement Range: -90<= latitude<= 90degrees
Bit 25	(LSB)	= $180/2^{23}$ degrees = $2.145767*10^{-05}$ degrees This corresponds to an accuracy of at least 2.3844 metres
Bits-24/1	(Longitude)	Longitude in WGS 84 expressed in two's complement Range: -180 <= longitude<180 degrees
Bit-1	(LSB)	= $180/2^{23}$ degrees = $2.145767*10^{-05}$ degrees This corresponds to an accuracy of at least 2.3844 metres

**Encoding Rule:**

See Table in I034/000.

### 5.3 Standard User Application Profile

5.3.1 The following standard UAP shown in Table 5 shall be used for the transmission of radar service messages:

**Table 5 - Standard UAP for Radar Service Messages**

FRN	Data Item	Data Item Description	Length in Octets
1	I034/010	Data Source Identifier	2
2	I034/000	Message Type	1
3	I034/030	Time-of-Day	3
4	I034/020	Sector Number	1
5	I034/041	Antenna Rotation Period	2
6	I034/050	System Configuration and Status	1+
7	I034/060	System Processing Mode	1+
FX	N/A.	Field Extension Indicator	N/A.
8	I034/070	Message Count Values	(1+2*N)
9	I034/100	Generic Polar Window	8
10	I034/110	Data Filter	1
11	I034/120	3D-Position of Data Source	8
12	I034/090	Collimation Error	2
13	RE-Data Item	Reserved Expansion Field	1+1+
14	SP-Data Item	Special Purpose Field	1+1+
FX	N/A.	Field Extension Indicator	n.a.

where:

- the first column indicates the FRN associated to each Data Item used in the UAP;
- the fourth column gives the format and the length of each item, a stand-alone figure indicates the octet count of a fixed-length Data Item, 1+ indicates a variable-length Data Item comprising a first part of one-octet followed by n-octets extent as necessary.